# On Voronoï's theorem and related problems 

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## Outline

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(2) Geometry of perfect forms
(3) Voronoï type theorem of the Rankin invariant
(4) Generalizations of Voronoï's theorem

## 1 Simple generalization of Voronoï's theorem

### 1.1 Voronoï's theorem

Let $V_{n}=\left\{a \in \mathrm{M}_{\boldsymbol{n}}(\mathbb{R}):{ }^{\boldsymbol{t}} \boldsymbol{a}=\boldsymbol{a}\right\}, \boldsymbol{P}_{\boldsymbol{n}}=\left\{a \in \boldsymbol{V}_{\boldsymbol{n}}: a>0\right\}$
Let $\boldsymbol{m}(\boldsymbol{a})=\inf _{0 \neq \boldsymbol{x} \in \mathbb{Z}^{\boldsymbol{n}}}{ }^{\boldsymbol{x}} \boldsymbol{x} \boldsymbol{a x}$ for $\boldsymbol{a} \in \overline{\boldsymbol{P}}_{\boldsymbol{n}}$, the closure of $\boldsymbol{P}_{\boldsymbol{n}}$.
The Hermite invariant $\boldsymbol{F}: \boldsymbol{P}_{\boldsymbol{n}} \longrightarrow \mathbb{R}_{>\boldsymbol{0}}$ is defined by

$$
F(a)=\frac{m(a)}{(\operatorname{det} a)^{1 / n}}
$$

Main Problem of Lattice Sphere Packings
Determine the actual value of the maximum $\gamma_{n}=\max _{\boldsymbol{a} \in \boldsymbol{P}_{\boldsymbol{n}}} \boldsymbol{F}(\boldsymbol{a})$.

Voronoï's theorem characterizes local maxima of $\boldsymbol{F}$.

Let $S(a)=\left\{x \in \mathbb{Z}^{\boldsymbol{n}}: a[x]=m(a)\right\}$, the set of minimal vectors. For $\boldsymbol{x} \in \mathbb{R}^{\boldsymbol{n}}$, let $\boldsymbol{\varphi}_{\boldsymbol{x}}: \boldsymbol{a} \mapsto \boldsymbol{a}[\boldsymbol{x}]={ }^{\boldsymbol{t}} \boldsymbol{x} \boldsymbol{a} \boldsymbol{x}$ be a linear form on $\boldsymbol{V}_{\boldsymbol{n}}$.

## Definition

Let $\sqrt{\boldsymbol{a}} \in \boldsymbol{P}_{\boldsymbol{n}}$ be the square root of $\boldsymbol{a} \in \boldsymbol{P}_{\boldsymbol{n}}$.

- $a$ is said to be perfect if $\left\{\varphi_{\sqrt{a} x}\right\}_{x \in S(a)}$ spanns $V_{n}^{*}$.
- $a$ is said to be eutactic if ${ }^{\exists} \rho_{x}>0, x \in S(a)$, such that

$$
\operatorname{Tr}=\sum_{x \in S(a)} \rho_{x} \varphi_{\sqrt{a} x}
$$

Theorem (Voronoï, 1908)
$\boldsymbol{F}(\boldsymbol{a})$ is a local maximum if and only if $\boldsymbol{a}$ is perfect and eutactic.

$$
\left(F=m / \operatorname{det}^{1 / n}\right)
$$

### 1.2 Generalization to type one functions

## Definition

A function $\phi: \overline{\boldsymbol{P}}_{\boldsymbol{n}} \longrightarrow \mathbb{R}_{\geq \mathbf{0}}$ is called a type one (class) function if

1. $\phi(\boldsymbol{\lambda} a)=\lambda \phi(a)$ for $a \in \overline{\boldsymbol{P}}_{\boldsymbol{n}}$ and $\boldsymbol{\lambda} \geq \mathbf{0}$.
2. $\phi(a+b) \geq \phi(a)+\phi(b)$ for $a, b \in \bar{P}_{\boldsymbol{n}}$.
3. $\boldsymbol{\phi}(\boldsymbol{a})>\mathbf{0}$ for $\boldsymbol{a} \in \boldsymbol{P}_{\boldsymbol{n}}$.
4. $\phi$ is upper semicontinuous on $\overline{\boldsymbol{P}}_{\boldsymbol{n}}$.
5. $\left(\phi(a[g])=\phi(a)\right.$ for $a \in P_{n}$ and $\left.g \in \mathbf{G L}_{\boldsymbol{n}}(\mathbb{Z}).\right)$

## Example

- Both $m$ and $\operatorname{det}^{1 / n}$ are type one class functions.
- If $\phi$ is a type one class function, then so is $\phi^{\circ}(a):=\inf _{b \in P_{n}} \frac{\operatorname{Tr}(a b)}{\phi(b)}$.

If $\phi$ is a type one function, then

- $\boldsymbol{\phi}$ is continuous on $\boldsymbol{P}_{\boldsymbol{n}}$
- $\phi$ is log-concave, i.e.,

$$
\log \phi(\lambda a+(1-\lambda) b) \geq \lambda \log \phi(a)+(1-\lambda) \log \phi(b)
$$

holds for ${ }^{\forall} \boldsymbol{a}, \boldsymbol{b} \in \boldsymbol{P}_{\boldsymbol{n}}$ and $\mathbf{0}<{ }^{\forall} \boldsymbol{\lambda}<\mathbf{1}$.
We say $\phi$ is strictly log-concave if this inequality is strict for all $\boldsymbol{a} \neq \boldsymbol{b}$.

We want to generalize Voronoï's theorem to $\boldsymbol{F}_{\phi}:=\boldsymbol{m} / \boldsymbol{\phi}$.
Assume $\boldsymbol{\phi}$ is differentiable on $\boldsymbol{P}_{\boldsymbol{n}}$. Then

$$
(\partial \log \phi)_{a}(v)=\lim _{t \rightarrow 0} \frac{\log \phi((\mathrm{I}+t v)[\sqrt{a}])-\log \phi(a)}{t}
$$

exists for $\boldsymbol{a} \in \boldsymbol{P}_{\boldsymbol{n}}$ and $\boldsymbol{v} \in \boldsymbol{V}_{\boldsymbol{n}}$.

## Definition

$\boldsymbol{a} \in \boldsymbol{P}_{\boldsymbol{n}}$ is said to be $\phi$-eutactic if ${ }^{\exists} \boldsymbol{\rho}_{\boldsymbol{x}}>\mathbf{0}, \boldsymbol{x} \in \boldsymbol{S}(\boldsymbol{a})$, such that

$$
(\partial \log \phi)_{a}=\sum_{x \in S(a)} \rho_{x} \varphi_{\sqrt{a} x}
$$

Theorem (Sawatani-W., 2009)
Assume a type one function $\phi$ is differentiable and strictly log-concave.
Then $\boldsymbol{F}_{\boldsymbol{\phi}}=\boldsymbol{m} / \boldsymbol{\phi}$ attains a local maximum on $\boldsymbol{a} \in \boldsymbol{P}_{\boldsymbol{n}}$ if and only if $\boldsymbol{a}$ is perfect and $\phi$-eutactic.

Question
Can we replace $\boldsymbol{m}$ with another type one function?

## 2 Geometry of perfect forms

### 2.1 Kernels

Definition
A subset $\boldsymbol{K} \subset \overline{\boldsymbol{P}}_{\boldsymbol{n}}$ is called a kernel if

1. $\boldsymbol{K}$ is a closed convex subset.
2. $\mathbf{0} \notin \boldsymbol{K}$.
3. $K=\mathbb{R}_{\geq 1} \cdot K$.
4. $\boldsymbol{P}_{\boldsymbol{n}} \subset \mathbb{R}_{\geq 0} \cdot \boldsymbol{K}$.

If $\phi$ is a type one function, then

$$
K_{1}(\phi):=\left\{a \in \bar{P}_{n}: \phi(a) \geq 1\right\}
$$

is a kernel.

Conversely, if $\boldsymbol{K}$ is a kernel, then

$$
\phi_{K}(a):=\max (\{\lambda>0: a \in \lambda K\} \cup\{0\})
$$

is a type one function.
These correspondences are inverse each other.

$$
\text { Type One Functions } \underset{\phi_{K} \leftarrow K}{\stackrel{\phi \rightarrow K_{1}(\phi)}{\leftrightarrows} \text { Kernels }}
$$

### 2.2 Ryshkov polyhedron

Recall $m(a)=\inf _{0 \neq x \in \mathbb{Z}^{n}} a[x]$ is a type one class function.
The kernel $\boldsymbol{K}_{\mathbf{1}}(\boldsymbol{m})$ is called the Ryshkov polyhedron.
We have

- $K_{1}(m) \subset P_{n}$.
- $\boldsymbol{K}_{\mathbf{1}}(\boldsymbol{m})$ is the intersection of affine half-spaces:

$$
K_{1}(m)=\bigcap_{x \in \mathbb{Z}^{n} \backslash\{0\}}\left\{a \in V_{n}: a[x] \geq 1\right\}
$$

- $K_{1}(\boldsymbol{m})$ is a locally finite polyhedron, i.e., the intersection of $K_{\mathbf{1}}(\boldsymbol{m})$ and an arbitrary polytope is a polytope.

Let $\boldsymbol{\partial} K_{1}(m)$ be the boundary of $K_{1}(m)$ and

$$
\mathcal{F}_{S(a)}:=\left\{b \in \partial K_{1}(m): S(a) \subset S(b)\right\} \quad \text { for } a \in P_{n}
$$

Theorem (Voronoï, Ryshkov, etal.)

- $\mathcal{F}_{S(a)}$ is a face of $K_{\mathbf{1}}(\boldsymbol{m})$. Any face of $\boldsymbol{K}_{\mathbf{1}}(\boldsymbol{m})$ is this form.
- $\mathcal{F}_{S(a)}$ is a vertex if and only if $\boldsymbol{a}$ is perfect.
- The set of all faces of $\boldsymbol{K}_{\mathbf{1}}(\boldsymbol{m})$ has finite $\mathbf{G L} \mathbf{L}_{\boldsymbol{n}}(\mathbb{Z})$-orbits.

Let $\partial^{0} K_{1}(m)$ be the set of all vertices of $K_{1}(m)$.

- $\mathbb{R}_{>0} \cdot \partial^{0} K_{1}(m)$ equals the set of all perfect forms.
- $K_{1}(m)$ is the convex hull of $\partial^{0} K_{1}(m)$.
- $\sharp\left(\partial^{0} K_{1}(m) / G L_{n}(\mathbb{Z})\right)$ is finite.



### 2.3 Local maximality of $S(a)$

Lemma
For $\boldsymbol{a} \in \boldsymbol{P}_{\boldsymbol{n}},{ }^{\exists} n b d \boldsymbol{O}_{a} \subset \boldsymbol{P}_{\boldsymbol{n}}$ of $\boldsymbol{a}$ such that $\boldsymbol{S}(\boldsymbol{b}) \subset \boldsymbol{S}(\boldsymbol{a})$ for ${ }^{\forall} \boldsymbol{b} \in O_{a}$.
We say $\boldsymbol{S}(\boldsymbol{a})$ is locally maximal if

$$
{ }^{\exists} O_{a} \text { such that } S(b) \varsubsetneqq S(a) \text { for }{ }^{\forall} b \in O_{a} \backslash \mathbb{R}_{>0} a \text {. }
$$

We can prove
$a$ is perfect $\Longleftrightarrow S(a)$ is locally maximal

Conclusion
$a$ is perfect $\Longleftrightarrow a \in \mathbb{R}_{>0} \cdot \partial^{0} K_{1}(m) \Longleftrightarrow S(a)$ is locally maximal

### 2.4 Existence of Hermite like constants

Let $\phi$ be a type one class function.
Since

1. $P_{n} \subset \mathbb{R}_{>_{0}} \cdot K_{1}(m)=\mathbb{R}_{>0} \cdot \partial K_{1}(m)$ and
2. $K_{1}(m)$ is the convex hull of $\partial^{0} K_{1}(m)$,
the Hermite like constant

$$
\begin{aligned}
\gamma_{\phi} & :=\sup _{a \in P_{n}} \frac{m(a)}{\phi(a)}=\sup _{a \in \partial K_{1}(m)} \frac{1}{\phi(a)} \\
& =\sup _{a \in \partial^{0} K_{1}(m)} \frac{1}{\phi(a)}=\max _{a \in \partial^{0} K_{1}(m) / \mathrm{GL}_{n}(\mathbb{Z})} \frac{1}{\phi(a)}
\end{aligned}
$$

exists.

Let $\phi^{\circ}(a)=\inf _{b \in P_{n}} \operatorname{Tr}(a b) / \phi(b)$, the dual of $\phi$.
Put $\xi_{\phi}=\gamma_{\phi} \cdot \gamma_{\phi^{0}}$.
Example

- $\xi_{\text {det }^{1 / n}}=\gamma_{n}^{2} / n$.
- $\xi_{m}=\max _{(a, b) \in P_{n} \times P_{n}} \frac{m(a) m(b)}{\operatorname{Tr}(a b)}$.

Theorem (Sawatani-W., 2009)
$\xi_{m} \leq \boldsymbol{\xi}_{\phi}$ for any type one class function $\phi$.

## 3 Voronoï type theorem of the Rankin invariant

### 3.1 Rankin's constant

Fix $1 \leq j \leq n-1$.
Let

$$
\mathrm{M}_{n, j}^{*}(\mathbb{Z})=\left\{\left(x_{1}, \cdots, x_{j}\right) \in \mathrm{M}_{n, j}(\mathbb{Z}): x_{1} \wedge \cdots \wedge x_{j} \neq 0\right\}
$$

Define the function $\boldsymbol{m}_{\boldsymbol{j}}: \overline{\boldsymbol{P}}_{\boldsymbol{n}} \longrightarrow \mathbb{R}_{\geq 0}$ by

$$
m_{j}(a)=\inf _{X \in \mathbf{M}_{n, j}^{*}(\mathbb{Z})}(\operatorname{det} a[X])^{1 / j}
$$

$\boldsymbol{m}_{\boldsymbol{j}}$ is a type one class function. The constant

$$
\gamma_{n, j}=\left(\max _{a \in P_{n}} F_{j}(a)\right)^{n}, \quad F_{j}(a)=\frac{m_{j}(a)}{(\operatorname{det} a)^{1 / n}}
$$

was introduced by Rankin(1953).

Explicit values (Rankin, 1953, Sawatani-W.-Okuda, 2008)

- $\gamma_{4,2}=3 / 2$.
- $\gamma_{6,2}=3^{2 / 3}, \gamma_{8,2}=3, \gamma_{8,3}=\gamma_{8,4}=4$.

Coulangeon characterized local maxima of $F_{j}=m_{j} / \operatorname{det}^{1 / n}$.
Theorem (Coulangeon, 1996)
$\boldsymbol{F}_{\boldsymbol{j}}(\boldsymbol{a})$ is a local maximum if and only if $\boldsymbol{a}$ is $\boldsymbol{j}$-perfect and $\boldsymbol{j}$-eutactic.

## $3.2 j$-perfection and $j$-eutaxy

Let $S_{j}^{*}(a)=\left\{X \in \mathrm{M}_{n, j}^{*}(\mathbb{Z}):(\operatorname{det} a[X])^{1 / j}=m_{j}(a)\right\}$.
Then $\boldsymbol{S}_{j}(a):=\boldsymbol{S}_{j}^{*}(a) / \mathbf{G} \mathbf{L}_{j}(\mathbb{Z})$ is a finite set.
Define the linear form $\varphi_{\boldsymbol{X}}: V_{n} \longrightarrow \mathbb{R}$ for $\boldsymbol{X} \in \mathrm{M}_{n, j}^{*}(\mathbb{Z})$ by

$$
\varphi_{X}(v)=\operatorname{Tr}\left(p_{X} \cdot v\right)
$$

where $\boldsymbol{p}_{\boldsymbol{X}}: \mathbb{R}^{\boldsymbol{n}} \longrightarrow \operatorname{span}\left(\boldsymbol{x}_{\boldsymbol{1}}, \cdots, \boldsymbol{x}_{\boldsymbol{j}}\right)$ is an orthogonal projection.
Definition

- $a$ is $j$-perfect if $\left\{\varphi_{\sqrt{a} X}\right\}_{[X] \in S_{j}(a)}$ spanns $V_{n}^{*}$.
- $a$ is $j$-eutactic if ${ }^{\exists} \rho_{\boldsymbol{X}}>\mathbf{0},[\boldsymbol{X}] \in \boldsymbol{S}_{\boldsymbol{j}}(\boldsymbol{a})$, such that

$$
\operatorname{Tr}=\sum_{[X] \in S_{j}(a)} \rho_{X} \varphi_{\sqrt{a} X}
$$

### 3.3 Some problems of $j$-perfect forms

Let $j \geq 2$. The kernel $K_{1}\left(m_{j}\right)=\left\{a \in P_{n}: m_{j}(a) \geq 1\right\}$ is bounded by hypersurfaces $\operatorname{det}(a[X])=1, X \in M_{n, j}^{*}(\mathbb{Z})$.

Problem 1
Determine locations of $\boldsymbol{j}$-perfect forms in $\boldsymbol{\partial} \boldsymbol{K}_{\mathbf{1}}\left(\boldsymbol{m}_{\boldsymbol{j}}\right)$.

Lemma
For $a \in P_{n},{ }^{\exists} n b d O_{a} \subset P_{n}$ of $a$ s.t. $S_{j}(b) \subset S_{j}(a)$ for ${ }^{\forall} b \in O_{a}$.

We can define the local maximality for $\boldsymbol{S}_{\boldsymbol{j}}(\boldsymbol{a})$.
Problem 2
$a$ is $j$-perfect $\stackrel{?}{\Longleftrightarrow} S_{j}(a)$ is locally maximal.

Let $\phi$ be a type one (class) function.
Problem 3
Characterize local maxima of $\boldsymbol{m}_{\boldsymbol{j}} / \boldsymbol{\phi}$ as Voronoi's theorem.

Problem 4
When is the Rankin like constant $\sup _{a \in P_{m}} \frac{m_{j}(a)}{\phi(a)}$ finite ?

## 4 Generalizations of Voronoï's theorem

### 4.1 Arithmetic or geometric generalizations

There are several works:

- Extensions of a base field from $\mathbb{Q}$ to algebraic number fields were studied by Coulangeon, Icaza, Leibak and others.
- Ash(1977) generalized the domain $\boldsymbol{P}_{\boldsymbol{n}}$ to an arbitrary self-dual homogeneous cone $\Omega$. The function $F=m / \operatorname{det}^{1 / n}$ is replaced with a packing function of $\boldsymbol{\Omega}$.
- Bavard $(1997,2005)$ extended a geometric framework underlying Voronoi's theorem.


### 4.2 Toward Voronoï's theorem for height functions

Let $\mathbf{k}$ be a global field, $\mathbf{G}$ a connected reductive algebraic group $/ \mathbf{k}$ and $\mathbf{P}$ a maximal k-parabolic subgroup of $\mathbf{G}$.
Let $\mathbf{G}_{\mathbb{A}}$ be the adele of $\mathbf{G}, \mathbf{K}_{\mathbb{A}}$ a max. compact subgroup of $\mathbf{G}_{\mathbb{A}}$.
We define the height $\boldsymbol{H}_{\mathbf{P}}: \mathbf{G}_{\mathbb{A}} \rightarrow \mathbb{R}_{>0}$ by

$$
H_{\mathrm{P}}(p h)=H_{\mathrm{P}}(p)=\left|\alpha_{\mathrm{P}}(p)\right|_{\mathbb{A}}^{-1}
$$

for $\boldsymbol{p} \in \mathbf{P}_{\mathbb{A}}$ and $\boldsymbol{h} \in \mathbf{K}_{\mathbb{A}}$, where $\boldsymbol{\alpha}_{\mathbf{P}}$ is a simple root associated with $\mathbf{P}$. Define $\boldsymbol{F}_{\mathbf{P}}: \mathbf{G}_{\mathbf{k}} \backslash \mathbf{G}_{\mathbb{A}} / \mathbf{K}_{\mathbb{A}} \rightarrow \mathbb{R}_{>0}$ by

$$
F_{\mathrm{P}}(g)=\min _{[v] \in \mathbf{P}_{\mathbf{k}} \backslash \mathrm{G}_{\mathbf{k}}} H_{\mathrm{P}}(v g)
$$

The maximum

$$
\gamma_{\mathbf{G}, \mathbf{P}}=\max _{[g] \in \mathbf{G}_{\mathbf{k}} \backslash \mathbf{G}_{\mathrm{A}} / \mathbf{K}_{\mathbb{A}}} F_{\mathbf{P}}(g)
$$

is called a generalized Hermite constant.
Example
If $\mathbf{k}=\mathbb{Q}, \mathbf{G}=\mathbf{G L}_{n}$ and $\mathbf{P}=\left\{\left(\begin{array}{cc}a & * \\ 0 & d\end{array}\right): a \in \mathbf{G L}_{j}, \boldsymbol{d} \in \mathbf{G L}_{n-j}\right\}$, then

$$
H_{\mathrm{P}}\left(\left(\begin{array}{ll}
a & * \\
0 & d
\end{array}\right)\right)=|\operatorname{det} a|_{\mathbb{A}}^{(j-n) / \operatorname{gcd}(j, n-j)}|\operatorname{det} d|_{\mathbb{A}}^{j / \operatorname{gcd}(j, n-j)}
$$

and

$$
\gamma_{\mathrm{G}, \mathrm{P}}=\left(\gamma_{n, j}\right)^{\frac{n}{2 \operatorname{gcd}(\boldsymbol{j}, n-j)}} .
$$

## Problem 5

Characterize local maxima of $\boldsymbol{F}_{\mathbf{P}}$ as Voronoï's theorem.

- If $\mathbf{k}$ is a number field, Bavard's theory applies to several cases, e.g., $\mathbf{G}=\mathbf{G L}_{\boldsymbol{n}}, \mathbf{S O}_{\boldsymbol{n}, \mathbf{1}}$, etc., so the problem was solved in some cases.
- The set of minimal vectors of $\boldsymbol{g} \in \mathbf{G}_{\mathbb{A}}$ is given by

$$
S_{\mathrm{P}}(g)=\left\{[v] \in \mathbf{P}_{\mathrm{k}} \backslash \mathrm{G}_{\mathrm{k}}: \boldsymbol{H}_{\mathrm{P}}(v g)=\boldsymbol{F}_{\mathbf{P}}(g)\right\}
$$

This is a finite subset of $\mathbf{P}_{\mathbf{k}} \backslash \mathbf{G}_{\mathbf{k}}$. We have

$$
{ }^{\exists} \mathrm{nbd} O_{g} \subset \mathrm{G}_{\mathbb{A}} \text { of } g \text { such that } S_{\mathrm{P}}\left(g^{\prime}\right) \subset S_{\mathrm{P}}(g) \text { for }{ }^{\forall} g^{\prime} \in O_{g}
$$

Thus we can define the local maximality of $\boldsymbol{S}_{\mathrm{P}}(\boldsymbol{g})$.

### 4.3 Example of $\gamma_{G, P}$ in the case of $\mathrm{G}=\mathrm{Sp}_{2 n} / \mathbb{Q}$

Let

$$
\begin{aligned}
& \mathbf{G}=\left\{g \in \mathbf{G L}_{2 n}:{ }^{t} g\left(\begin{array}{cc}
0 & -\mathbf{I} \\
\mathbf{I} & 0
\end{array}\right) g=\left(\begin{array}{cc}
0 & -\mathbf{I} \\
\mathbf{I} & 0
\end{array}\right)\right\}, \\
& \mathbf{P}=\left\{\left(\begin{array}{cc}
a & * \\
0 & { }^{t} a^{-1}
\end{array}\right): a \in \mathbf{G L}_{n}\right\} .
\end{aligned}
$$

The rational character $\alpha_{P}: \mathbf{P} \longrightarrow \mathbf{G L}_{\mathbf{1}}$ is given by

$$
\alpha_{P}\left(\left(\begin{array}{cc}
a & * \\
0 & { }^{t} a^{-1}
\end{array}\right)\right)=\operatorname{det} a
$$

Since $\mathbf{G}$ and $\mathbf{P}$ satisfy

1. $\mathbf{G}_{\mathbb{A}}=\mathbf{G}_{\mathbb{Q}} \cdot \mathbf{G}_{\mathbb{R}} \cdot \mathbf{K}_{\mathbb{A}}$ (strong approximation),
2. $\mathbf{G}_{\mathbb{Q}}=\mathbf{P}_{\mathbb{Q}} \cdot \mathbf{G}_{\mathbb{Z}}$,
one has

$$
\begin{aligned}
\gamma_{\mathbf{G}, \mathbf{P}} & =\max _{[g] \in \mathbf{G}_{\mathbb{Q}} \backslash \mathbf{G}_{\mathbb{A}} / \mathbf{K}_{\mathbb{A}}} \min _{\boldsymbol{v}] \in \mathbf{P}_{\mathbb{Q}} \backslash \mathbf{G}_{\mathbb{Q}}} H_{\mathbf{P}}(v g) \\
& =\max _{[g] \in \mathbf{G}_{\mathbb{Z}} \backslash \mathbf{G}_{\mathbb{R}} / \mathbf{K}_{\infty}} \min _{\gamma \in \mathbf{G}_{\mathbb{Z}}} H_{\mathbf{P}}^{\infty}(\gamma \boldsymbol{r}),
\end{aligned}
$$

where $\boldsymbol{H}_{\mathrm{P}}^{\boldsymbol{\infty}}(\boldsymbol{p h})=\left|\boldsymbol{\alpha}_{\mathbf{P}}(\boldsymbol{p})\right|^{-1}$ for $\boldsymbol{p} \in \mathbf{P}_{\mathbb{R}}, \boldsymbol{h} \in \mathbf{K}_{\infty}$.

Let $\mathbf{H}_{n}=\left\{Z \in \mathbf{M}_{\boldsymbol{n}}(\mathbb{C}): \operatorname{Re} Z \in V_{n}, \operatorname{Im} Z \in P_{n}\right\}$.
The group $\mathbf{G}_{\mathbb{R}}$ acts on $\mathbf{H}_{\boldsymbol{n}}$ by

$$
g\langle Z\rangle=(a Z+b)(c Z+d)^{-1}, \quad\left(g=\left(\begin{array}{ll}
a & b \\
c & d
\end{array}\right), Z \in \mathbf{H}_{n}\right)
$$

Then we have

$$
H_{\mathrm{P}}^{\infty}(g)=(\operatorname{det} \operatorname{Im}\{g\langle\sqrt{-1} \mathrm{I}\rangle\})^{-1 / 2} \quad\left(g \in \mathrm{G}_{\mathbb{R}}\right)
$$

and

$$
\gamma_{\mathbf{G}, \mathbf{P}}=\max _{[g] \in \mathbf{G}_{\mathbb{Z}} \backslash \mathbf{G}_{\mathbb{R}} / \mathbf{K}_{\infty}} \min _{\gamma \in \mathbf{G}_{\mathbb{Z}}}(\operatorname{det} \operatorname{Im}\{\gamma g\langle\sqrt{-1} \mathbf{I}\rangle\})^{-1 / 2} .
$$

Since $\boldsymbol{g}\langle\sqrt{-\mathbf{1}} \mathbf{I}\rangle$ runs over a fundamental domain of $\mathbf{G}_{\mathbb{Z}} \backslash \mathbf{H}_{\boldsymbol{n}}$, we have

$$
\begin{aligned}
\gamma_{\mathbf{G}, \mathbf{P}}^{-2} & =\min _{[Z] \in \mathbf{G}_{\mathbb{Z}} \backslash \mathbf{H}_{n}} \max _{\gamma \in \mathbf{G}_{\mathbb{Z}}} \operatorname{det} \operatorname{Im}\{\gamma\langle Z\rangle\} \\
& =\min _{Z \in \mathbf{S}_{n}} \max _{\left(\begin{array}{cc}
a & b \\
c & d
\end{array}\right) \in \mathbf{G}_{\mathbb{Z}}} \frac{\operatorname{det} \operatorname{Im} Z}{|\operatorname{det}(c Z+d)|^{2}},
\end{aligned}
$$

where $\mathbf{S}_{\boldsymbol{n}}$ is Siegel's fundamental domain:
$\left\{\begin{array}{ll}\left.Z=X+\sqrt{-1} Y: \begin{array}{l}\bullet|\operatorname{det}(c Z+d)| \geq 1 \\ \\ \bullet\left|x_{i j}\right| \leq 1 / 2, \quad Y \in\left(\begin{array}{l}\forall \\ \forall\end{array}\binom{*}{c d} \in \mathrm{G}_{\mathbb{Z}}\right. \\ \text { Minkowski's domain })\end{array}\right\}\end{array}\right\}$
From

$$
Z \in \mathbf{S}_{n} \Longrightarrow \max _{\gamma \in \mathbf{G}_{\mathbb{Z}}} \operatorname{det} \operatorname{Im}\{\gamma\langle Z\rangle\}=\operatorname{det} \operatorname{Im} Z
$$

it follows

$$
\gamma_{\mathbf{G}, \mathbf{P}}^{-2}=\min _{Z \in \mathrm{~S}_{n}} \operatorname{det} \operatorname{Im} Z
$$

When $n=1, \min _{Z \in S_{1}} \operatorname{det} \operatorname{Im} Z=\sqrt{3} / 2$.
When $\boldsymbol{n}=\mathbf{2}$, Takashi Kawamura determined $\min _{Z \in \mathbf{S}_{\mathbf{2}}} \operatorname{det} \operatorname{Im} Z$ by using Gottschling's description of $\mathbf{S}_{\mathbf{2}}$.

Theorem (Kawamura, 2009)
$\min _{Z \in S_{2}} \operatorname{det} \operatorname{Im} Z=2 / 3$.
This minimum is attained only when $Z=Z_{8}$ or $-\overline{Z_{8}}$, where

$$
Z_{8}=\frac{1}{3}\left(\begin{array}{cc}
1 & -1 \\
-1 & 1
\end{array}\right)+\frac{\sqrt{2}}{3}\left(\begin{array}{ll}
2 & 1 \\
1 & 2
\end{array}\right) \sqrt{-1} .
$$

The domain $\mathbf{S}_{\mathbf{2}}$ is described by 28 polynomials in 6 real variables. Hayata computed 0-dimensional cells of the boundary $\boldsymbol{\partial} \mathbf{S}_{\mathbf{2}}$ of $\mathbf{S}_{\mathbf{2}}$. There are at least 5260 -dimensional cells of $\boldsymbol{\partial \mathbf { S } _ { \mathbf { 2 } }}$. Both $Z_{8}$ and $-\overline{Z_{8}}$ are contained in Hayata's list.

## Appendix: Bavard's theory

We consider a quadruplet $\mathcal{E}=\left(\boldsymbol{V}, \boldsymbol{\Gamma}, \boldsymbol{C},\left\{f_{s}\right\}\right)$ :
$\boldsymbol{V}$ : Riemannian manifold,
$\boldsymbol{\Gamma}$ : discrete subgroup of the isometry group of $\boldsymbol{V}$,
$C:$ index set endowed with a right action of $\Gamma$,
$\left\{f_{s}\right\}$ : family of $C^{1}$ functions $f_{s}: V \rightarrow \mathbb{R}$ parametrized by $s \in C$.

Assume

1. $f_{s} \circ \gamma=f_{s \gamma}$ for ${ }^{\forall} s \in C$ and ${ }^{\forall} \gamma \in \Gamma$.
2. $\sharp\left\{s \in C: f_{s}(v) \leq \lambda\right\}$ is finite for ${ }^{\forall} \boldsymbol{v} \in \boldsymbol{V}$ and ${ }^{\forall} \boldsymbol{\lambda} \in \mathbb{R}$.

What we do is to characterize local maxima of the function $F_{\mathcal{E}}: v \mapsto \min _{s \in C} f_{s}(v)$.

For $\boldsymbol{v} \in \boldsymbol{V}$, let
$\boldsymbol{T}_{\boldsymbol{v}}=$ tangent space of $\boldsymbol{V}$ at $\boldsymbol{v}$, $X_{s}(v)=\left(\operatorname{grad} f_{s}\right)(v)$, $S_{\mathcal{E}}(v)=\left\{s \in C: f_{s}(v)=F_{\mathcal{E}}(v)\right\}$,
$\operatorname{Conv}(v)=$ convex hull of $\left\{\boldsymbol{X}_{\boldsymbol{s}}(v)\right\}_{s \in S_{\mathcal{E}}(v)}$ in $\boldsymbol{T}_{\boldsymbol{v}}$,
$\operatorname{Aff}(v)=$ affine subspace spanned by $\left\{X_{s}(v)\right\}_{s \in S_{\mathcal{E}}(v)}$ in $\boldsymbol{T}_{\boldsymbol{v}}$.

## Definition

- $\boldsymbol{v}$ is said to be perfect if $\boldsymbol{T}_{\boldsymbol{v}}=\operatorname{Aff}(\boldsymbol{v})$.
- $\boldsymbol{v}$ is said to be eutactic if $\mathbf{0} \in \operatorname{Conv}(\boldsymbol{v})$.

We say $\mathcal{E}$ has the Voronoï property if the equivalence
$\boldsymbol{F}_{\mathcal{E}}$ attains a local maximum on $\boldsymbol{v} \Longleftrightarrow \boldsymbol{v}$ is perfect and eutactic.
holds.

Theorem (Bavard)
Assume $f_{s}$ is convex on any geodesic line on $\boldsymbol{V}$ for all $s$, i.e.,

$$
f_{s}(\ell(\lambda \alpha+(1-\lambda) \beta)) \leq \lambda f_{s}(\ell(\alpha))+(1-\lambda) f_{s}(\ell(\beta))
$$

holds for any geodesic $\boldsymbol{\ell}:[\mathbf{0}, \boldsymbol{\epsilon}) \rightarrow \boldsymbol{V}, \boldsymbol{\alpha}, \boldsymbol{\beta} \in(\mathbf{0}, \boldsymbol{\epsilon})$ and $\mathbf{0}<\boldsymbol{\lambda}<\mathbf{1}$.
Then $\mathcal{E}$ has the Voronoï property.

## Example

Let $P_{n}^{1}=\left\{a \in P_{n}: \operatorname{det} a=1\right\} \cong S L_{n}(\mathbb{R}) / S O_{n}(\mathbb{R})$.
$\mathcal{E}=\left(P_{n}^{1}, S L_{n}(\mathbb{Z}), \mathbb{Z}^{\boldsymbol{n}} \backslash\{0\},\left\{\varphi_{x}\right\}\right)$ has the Voronoï property. Here $\varphi_{x}(a)=a[x]$.

## Example

Let $G$ be a connected Lie subgroup of $S L_{n}(\mathbb{R})$ and $\boldsymbol{G} \cdot \mathrm{I}$ be the $\boldsymbol{G}$-orbit of $\mathbf{I}$ in $P_{n}^{\mathbf{1}}$. If $\boldsymbol{G}$ is invariant by the transpose $\boldsymbol{g} \mapsto{ }^{\boldsymbol{t}} \boldsymbol{g}$, then $\mathcal{E}=\left(G \cdot \mathrm{I}, G \cap S L_{n}(\mathbb{Z}), \mathbb{Z}^{n} \backslash\{0\},\left\{\left.\varphi_{x}\right|_{G \cdot I}\right\}\right)$ has the Voronoï property.

